

## AMALYSES 2 5 March 2024

Warm-up: Calculate  $\frac{d}{dx} \left[ \sin(x^4 + 5^3) + 5x^2 \right]$ .



The first half of year will focus on "multi-variable calculus".

- path integrals 0
- partial derivatives and directional derivatives 0
- local extremes of multi-variable functions 0
- double integrals 0

The second half of the year will focus on "differential equations". vocab for ODEs and IVPs in general

- 0
- separable ODEs 0
- first-order linear ODEs 3
- higher-order linear ODEs with constant coefficients 0



## Calculations vs. Ideas

In Analysis 1, I often tried to focus on *ideas first*. learned the Product Rule.

For some topics this year, I'm going to do calculations first. We will do calculations like

$$\frac{\partial}{\partial y} \left[ x^5 y^9 \right] = 9x^5 y^8$$

without worrying—at first—about what they mean or what problems could be solved using those calculations. That discussion will come later.

# For example, I talked about finding min / max using critical points before we

and 
$$\int_{0}^{1} \int_{3}^{5} xy \, dx \, dy = 4$$





Quizzes worth 5 points each

- 6 total. Lowest is dropped. 0
- each quiz is still 5 / 5. (Details on next slide.)

Exams worth 15 points each

Exam 2 might be last day of class (with second attempt during the 0 University's exam period). Will be decided later.

Participation worth 5 points

# There will also be "bonus points" from Portal, but the maximum score for



#### Quizzes — details

- score on each quiz is 5 points.
- On most weekends, ePortal will have a single "bonus" task.

  - the in-class quiz!

Realistically, I know students can cheat on online tasks. If you do, you might earn the 1 point, but you will not understand the material as well, so you will probably not do well on the in-class quiz!

#### There will be in-class quizzes approximately every two weeks. The maximum

If you answer the ePortal task correctly, you earn an extra point on the quiz, so you could make a small mistake in class and still get full credit. If you answer the ePortal task incorrectly, you can still get 5 / 5 from





#### There are $6 \times 5 + 15 + 15 + 5 = 60$ total possible points.

Points	[0, 30)	[30, 36)	[36, 42)	[42, 48)	[48, 54)	[54, 60]
Grade	2.0	3.0*	3.5*	4.0	4.5	5.0

- You can work together on task lists (which are not graded). Quizzes and exams should be individual.
- Cheating on in-class quiz  $\rightarrow$  quiz grade 0. Ø
- Cheating on exam  $\rightarrow$  course grade 2.0. 0 More than 5 unexcused absences after this week  $\rightarrow$  course grade 2.0.

\* Passing also requires at least 12 points from each "half" of the course.





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#### Department of Accessibility and Support for People with Disabilities (DDO)

Of course math has numbers:  $\circ 5$   $\circ \frac{1}{2}$   $\circ \pi^2$   $\circ \ln(3)$ 

These are also called scalars sometimes.

You have hopefully also seen vectors • [5,0,2] •  $5\hat{\imath} + 2\hat{k}$  these are •  $3\hat{\imath} - 4\hat{\jmath}$  • -62/9 and matrices the same 

in other classes.







We will only use two important vector ideas/calculations in this class: 1) The **length** or magnitude of the vector  $\vec{v} = [a, b, c]$  is written as  $|\vec{v}|$  and is calculated as

A unit vector has length 1.

 $\vec{b} = [b_1, b_2, b_3]$  is written as  $\vec{a} \cdot \vec{b}$  and has two formulas:  $\vec{a} \cdot \vec{b} = a_1 b_1 + a_2 b_2 + a_3 b_3,$ where  $\theta$  is the angle between the two vectors.

## $\left| \vec{v} \right| = \sqrt{a^2 + b^2 + c^2}.$

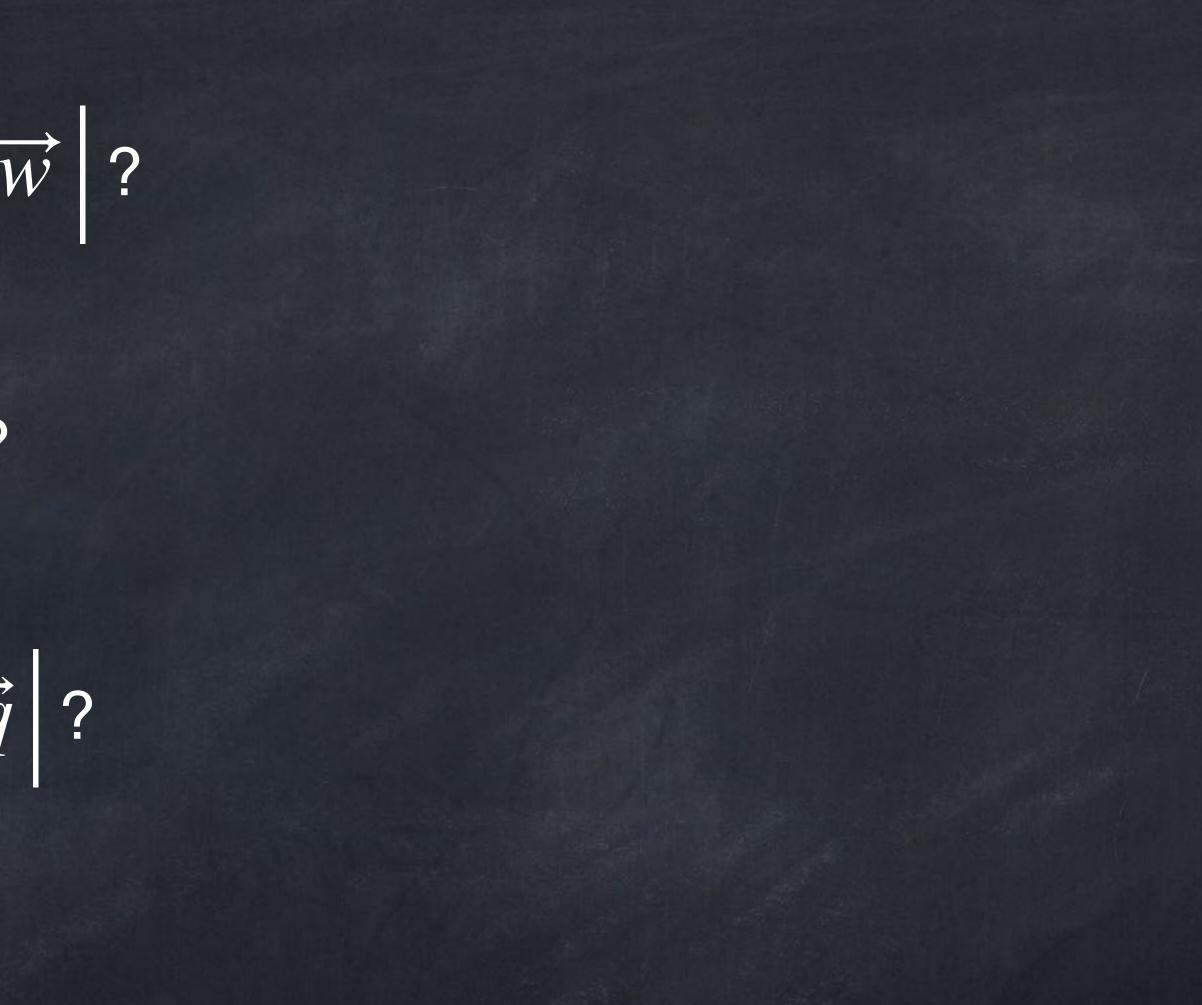
• If s > 0 is a scalar, then  $|\vec{sv}| = s |\vec{v}|$ . 2) The dot product or scalar product of two vectors  $\vec{a} = [a_1, a_2, a_3]$  and

$$\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos(\theta),$$



Task 1: If  $\vec{w} = -5\hat{\imath} + 2\hat{\jmath}$ , what is  $|\vec{w}|$ ? Answer: 129 Task 2: If  $\vec{v} = a\hat{i} + b\hat{j}$ , what is  $|\vec{v}|$ ? Answer:  $\sqrt{a^2 + b^2}$ Task 3: If  $\vec{q} = 4n\hat{i} + p^3\hat{j}$ , what is  $|\vec{q}|$ ? Answer:  $\sqrt{16n^2 + p^6}$ 

The last task might look strange because has several variables, but it's really exactly the same formula (the Pythagorean formula) you would use to find the longest side of a right triangle!

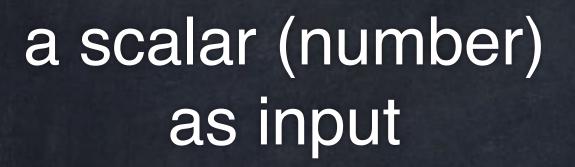




#### The functions • $f(x) = x^3$ • $g(x) = 2e^{9x}$ • $h(t) = t^8 + \ln(1 + \cos(1/t))$ • f(x) = sin(x)all have <u>one input and one output</u>. (We can write $f: \mathbb{R} \to \mathbb{R}$ for this.)

We can graph these kinds of functions on a 2D drawing, and we can find the derivative, the tangent line at a point, the indefinite or definite integral, etc.

Now we will start looking at functions with <u>multiple</u> inputs, so  $f: \mathbb{R}^n \to \mathbb{R}$ .





a vector (or multiple numbers) as input

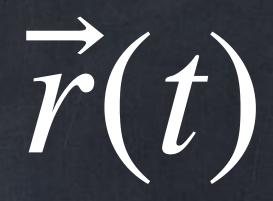


## a scalar (number) as output

x(t)

P(x)

#### a vector (or multiple numbers) as output



F(x, y, z)

#### a scalar (number) as input

a vector (or multiple numbers) as input

"scalar function" or "scalar field"

#### a scalar (number) as output

#### a vector (or multiple numbers) as output

"vector function" (also used for parametric curves)

"vector field"

## A function $\mathbb{R}^n \to \mathbb{R}$ is called a scalar function. For functions $\mathbb{R}^2 \to \mathbb{R}$ we often write

although the letters do not have to be "f" and "x" and "y". These often come from physical descriptions:

• 
$$r(x,y) = \sqrt{x^2 + y^2}$$

• 
$$P(\ell, w) = 2\ell + 2w$$

•  $K(m,v) = \frac{1}{2}mv^2$ 

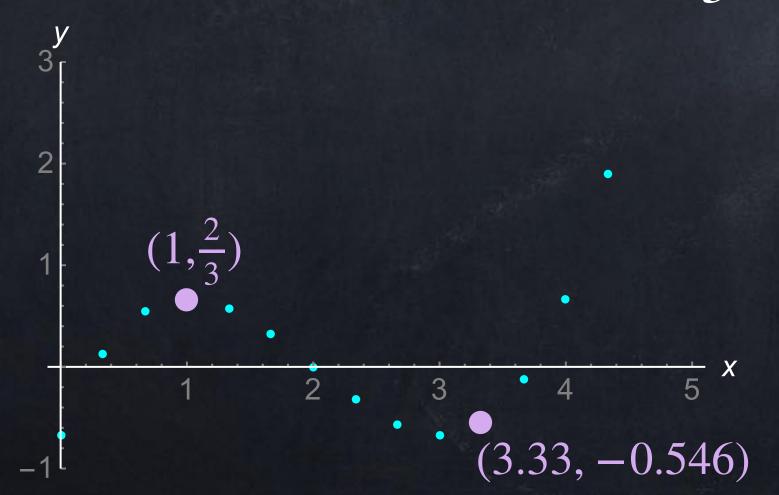
We can have even more inputs, such as

- f(x, y)
- distance from (x,y) to the origin
- perimeter of length L, width w rectangle
- kinetic energy for mass m and speed v
- T(x, y, z, t) temperature at different places and times



## The graph of a function f(x) is the set of all points (x, y) in 2D for which y = f(x).

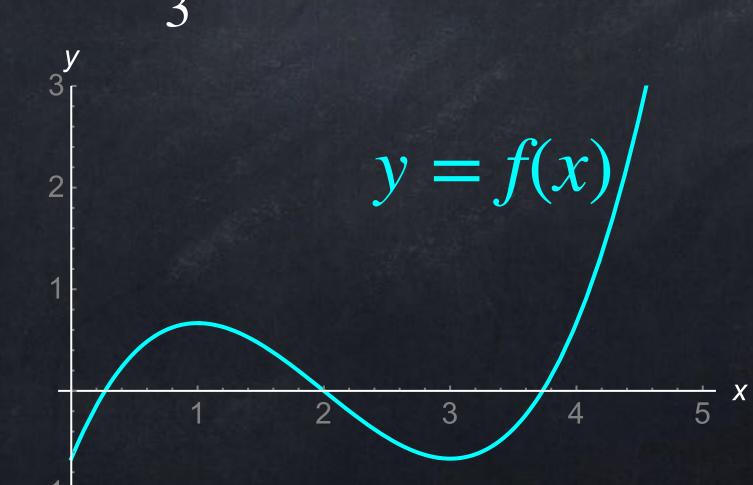
the vertical axis.



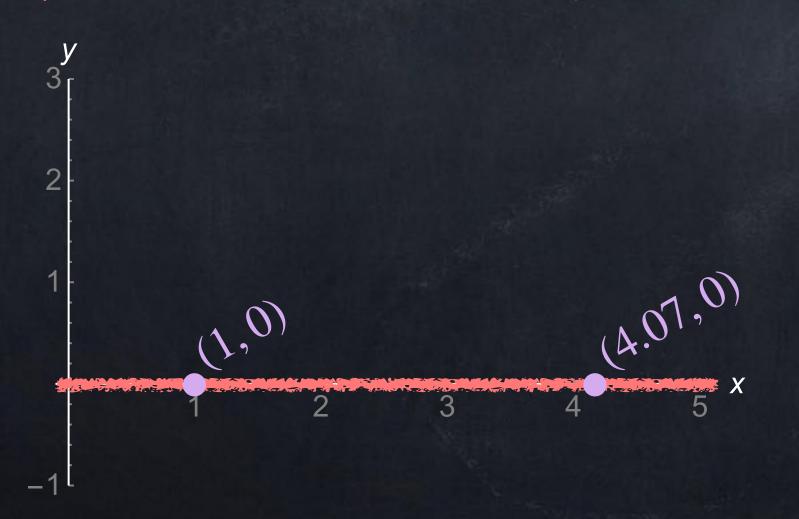
# Graphs of functions

#### We draw this on a plot with the input on the horizontal axis and the output on

 $f(x) = \frac{1}{3}x^3 - 2x^2 + 3x - \frac{2}{3}$ 



## The x-axis has all points with y=0.





20,1.83)

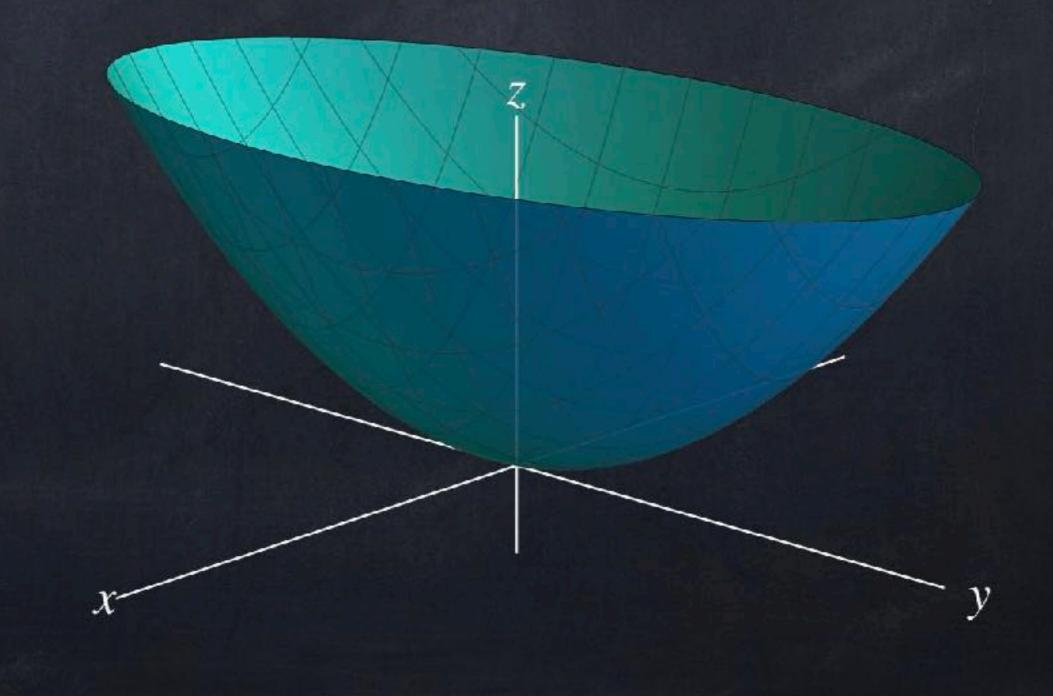
# The y-axis has all points with x=0.

2

5

## For a function with *two* inputs, we need a 3D picture for the graph. The graph of f(x, y) is the set of points (x, y, z) in 3D for which z = f(x, y).

Example: The graph of  $f(x, y) = 4x^2 + y^2$ , drawn from two perspectives:



#### The "coordinate axes" and the "coordinate planes" in 3D are these:

## the *x*-axis

x = 0

X

 $\mathcal{X}$ 

y = 0

# the yz-plane

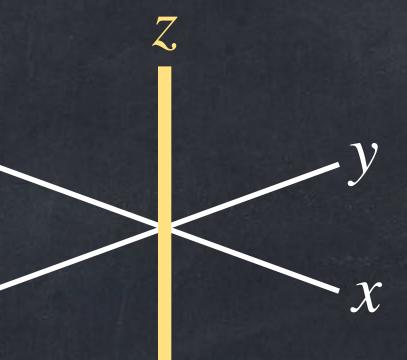


 ${\mathcal X}$ 

V

X

Z



#### the z-axis

#### the *xy*-plane

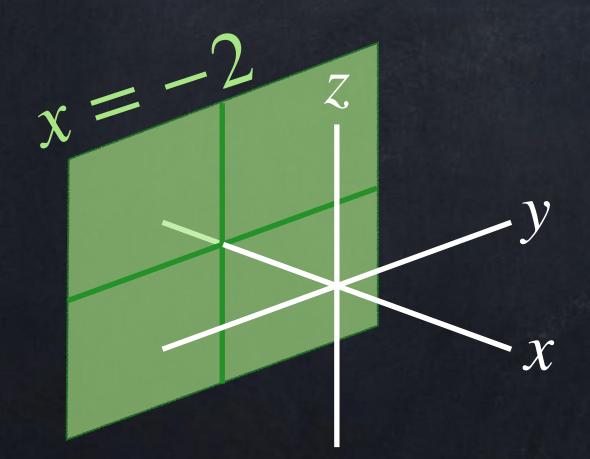
 $\overline{\mathcal{X}}$ 

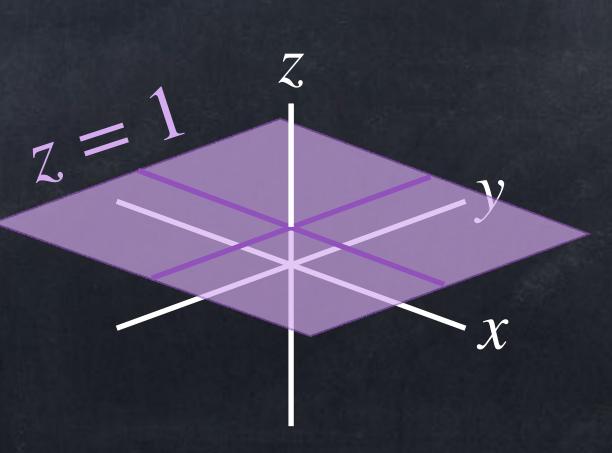
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#### the *xz*-plane

In general, equations of planes can look like Ax + By + Cz = D (you might have seen this in your Linear Algebra class). A plane that is parallel to a coordinate plane has a much more simple formula. Examples: The plane x = -2 is parallel to the yz-plane (which is x = 0). 0

• The plane z = 1 is parallel to the xy-plane (which is z = 0).







A curve in 2D space might be described as a graph, like  $y = x^3 - x$ , but some curves are easier to describe with "parametric equations". For example, the parametric equations

•  $x(t) = \cos t$ ,  $y(t) = \sin t$ with  $-\frac{3\pi}{4} \le t \le \frac{\pi}{4}$  draw part of the circle  $x^2 + y^2 = 1$ .

•  $x(t) = 8 \cos t$ , y(t) = 3,  $z(t) = 8 \sin t$ describes a circle that is in a vertical plane (the plane y = 3).

In 3D, curves are almost always described by parametric equations. Example:



Instead of listing separate equations for x and y, we can also write a set of parametric equations as a single vector equation. For example, •  $x(t) = \cos t$ ,  $y(t) = e^{10t}$ NOTE: We use  $\vec{r}$  to mean either [x, y]or [x, y, z] depending on context. is the same as •  $\vec{r}(t) = (\cos t)\hat{\imath} + e^{10t}\hat{\jmath}$ .

We can do algebra with this function. For example,

$$\vec{r}(t) = \sqrt{(\cos t)^2 + e^{20t}}$$

We can also do analysis with this function! For example, •  $\vec{r}'(t) = (-\sin t)\hat{\imath} + 10e^{10t}\hat{\jmath}.$ 



Although we never did this, it's also possible to write  $x \, dx = 18$ , where I = [0,6] or  $I = \{x : 0 \le x \le 6\}$ .

using a single letter for an interval. This is "the integral of x 'over' the interval I".

For  $f: \mathbb{R}^n \to \mathbb{R}$  we will only have definite integrals.

# Analysis 1 integrals For f(x), we had indefinite integrals, like $\int x \, dx = \frac{1}{2}x^2 + C$ , and we had definite integrals, like $\int_0^6 x \, dx = 18$ .





If the letter C is used for a curve, the over the curve C is written as

This can also be called "line integral" or "curve integral" or "curvilinear integral". Questions:

• What does this physically mean?  $\rightarrow$  Next week • How do we calculate this?  $\rightarrow$  Today Answer:  $\int_{a}^{b} f(\vec{r}(t)) \left| \vec{r}'(t) \right| dt$  if the curve *C* is described by  $\vec{r} : [a, b] \rightarrow \mathbb{R}^{n}$ .

#### If the letter C is used for a curve, then the path integral of the function f(x, y)

f(x, y) ds.



#### Example 1: Calculate

for  $0 \leq t \leq \frac{\pi}{2}$ .

The integral is  $\int_{0}^{\pi/2} (3\cos t)e^{2}(3\sin t) \ 3 \ dt = \frac{3}{2}e^{6\sin t}\Big|_{t=0}^{t=\pi/2} = \frac{3}{2}(e^{6}-1).$ 

Path integral

 $xe^{2y} ds$ 

#### where C is the curve with parametric equations $x(t) = 3 \cos t$ , $y(t) = 3 \sin t$

# $\vec{r} = [3\cos t, 3\sin t]$ , so $\vec{r}' = [-3\sin t, 3\cos t]$ and $|\vec{r}'|$ simplifies to 3.

calculation: 
$$\int_{C} f \, ds = \int_{a}^{b} f(\vec{r}(t)) \left| \vec{r}'(t) \right|$$





# Example 2: Calculate the path integral of

over the curve given by



 $f(x, y) = \sqrt{1 + 4x^2}$ 

## x = t, $y = t^2$ , $0 \le t \le 1$ .

r b Path integral calculation:  $\int_{C} f ds = \int_{a} f(\vec{r}(t)) \left| \vec{r}'(t) \right| dt$ 







For a function of one variable, the derivative of f(x) can be written as any of f'(x) f'  $\frac{d}{dx}[f]$   $\frac{df}{dx}$ and is a new function. There is also the derivative at a point, which is just a number (the slope of the tangent line to y = f(x) at the x-value).

The derivative is originally defined as a limit,  $f'(x) = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$ , but we don't use that formula once we learn rules like  $\frac{\mathrm{d}}{\mathrm{d}x}[x^p] = px^{p-1}, \qquad \frac{\mathrm{d}}{\mathrm{d}x}[\sin(x)] = \cos(x), \qquad \frac{\mathrm{d}}{\mathrm{d}x}[\ln(x)] = \frac{1}{x}.$ 

if p is constant

For a function f(x, y) we can change x or change y (or both at once — more on that later), so we have multiple ways to take derivatives.

The partial derivative of f(x, y) with respect to x can be written as any of  $f'_{x}(x,y) \qquad f'_{x}$ and is what you get if you think of every letter other than x as a constant.



 $\frac{\partial f}{\partial x}$  $\partial_{\mathbf{r}} f$  $D_{r}f$ 

Like with f'(x) and f'(a), we also have the partial derivative of f with respect to x at the point (a,b), which is a single number; we write this as  $f'_{x}(a,b)$ .



# To calculate the partial derivative (function) of f(x, y) with respect to x, we just pretend that any variable other than x is a constant.

$$\frac{\partial}{\partial x} \left[ \sin(x^4 + y^3) + x^2 y \right] =$$

It might help to think of functions with one variable and a similar format....



To calculate the partial derivative (function) of f(x, y) with respect to x, we just pretend that any variable other than x is a constant.

 $\frac{\mathrm{d}}{\mathrm{d}x} \left[ \sin(x^4 + 5^3) + 5x^2 \right] = \cos(x^4 + 5^3) \cdot 4x^3 + 10x$ 

 $\frac{\partial}{\partial x} \left[ \sin(x^4 + k^3) + kx^2 \right] = \cos(x^4 + k^3) \cdot 4x^3 + 2kx$ 

 $\frac{\partial}{\partial x} \left[ \sin(x^4 + y^3) + x^2 y \right] = \cos(x^4 + y^3) \cdot 4x^3 + 2xy$ 



To calculate the partial derivative (function) of f(x, y) with respect to x, we just pretend that any variable other than x is a constant.

 $(\sin(x^4 + 5^3) + 5x^2)' = \cos(x^4 + 5^3) \cdot 4x^3 + 10x$ 

## $(\sin(x^4 + k^3) + kx^2)'_x = \cos(x^4 + k^3) \cdot 4x^3 + 2kx$

 $(\sin(x^4 + y^3) + x^2y)'_x = \cos(x^4 + y^3) \cdot 4x^3 + 2xy$ 



# think of every letter other than y as a constant (that includes x!).

There is also the partial derivative of f(x, y) with respect to y, in which we

## $(\sin(8^4 + t^3) + 8^2t)' = \cos(8^4 + t^3) \cdot 3t^2 + 8^2$

## $(\sin(8^4 + y^3) + 8^2y)'_{y} = \cos(8^4 + y^3) \cdot 3y^2 + 8^2$

 $(\sin(x^4 + y^3) + x^2y)'_v = \cos(x^4 + y^3) \cdot 3y^2 + x^2$ 

# think of every letter other than y as a constant (that includes x!).

# $\frac{d}{dt} \left[ \sin(8^4 + t^3) + 8^2 t \right] = \cos(8^4 + t^3) \cdot 3t^2 + 8^2$

 $\frac{d}{dv} \left[ \sin(8^4 + y^3) + 8^2 y \right] = \cos(8^4 + y^3) \cdot 3y^2 + 8^2$ 

 $\frac{\partial}{\partial y} \left[ \sin(x^4 + y^3) + x^2 y \right] = \cos(x^4 + y^3) \cdot 3y^2 + x^2$ 

There is also the partial derivative of f(x, y) with respect to y, in which we

